

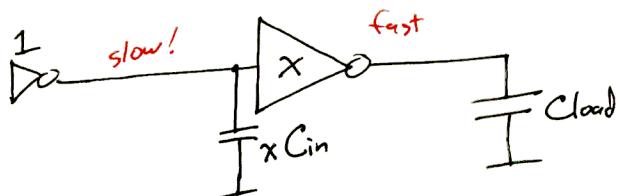
### Sizing a Chain of inverters

Problem: a logic signal needs to drive a large load ( $C_{load}$ ), such as bringing a signal off chip to a circuit board.

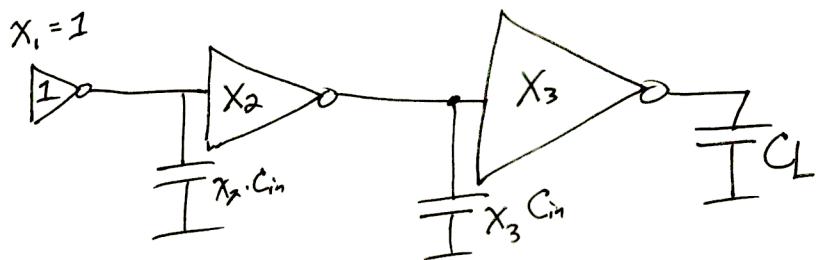


Inverter (base size) is small  $\rightarrow R_{out}$  is large,  $C$  is large, so delay is really long. ( $R_{out} \cdot C_{load}$ )

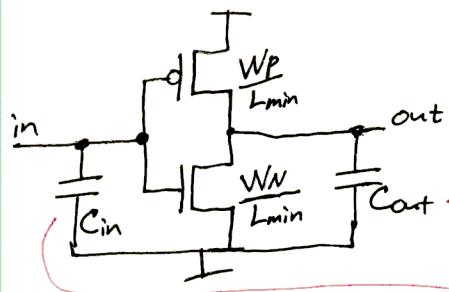
Use a large (transistor width) inverter!  
But something needs to drive this inverter's (now large) input  $C_{in}$ .



So, use a not so large inverter to drive the large one



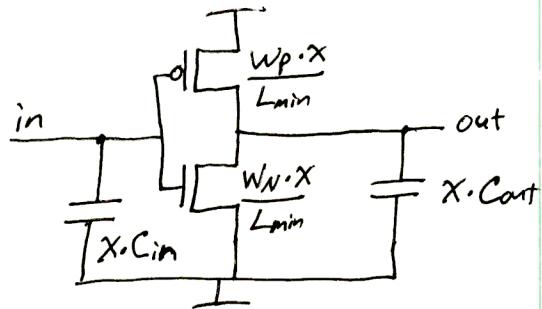
? How many stages to use and how to choose the  $x_i$ 's?  
↳ this is an optimization problem

Base-sized inverter

$$\text{usually } W_p \approx 2 \cdot W_N$$

so ON resistances / drive strengths  
are about the same

$$R_N \approx R_p = \underline{R}$$

Larger drive strength inverter

$$R_{\text{drive}} = \frac{R}{X}$$

$$C_{inX} = X \cdot C_{in}$$

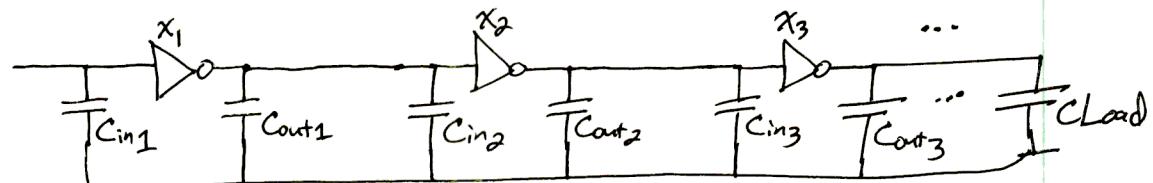
$$C_{outX} = X \cdot C_{out}$$

Inverter delay

$$d = (\text{constant}) \cdot \frac{R}{X} \left( X \cdot C_{out} + C_{load} \right)$$

$$= (\text{constant}) \left( R \cdot C_{out} + \frac{R \cdot C_{load}}{X} \right)$$

$\underbrace{\hspace{100px}}$   
base value  
parasitic  
constant!
 $\underbrace{\hspace{100px}}$   
due to load



$$\text{Total delay} = \sum_{i=1}^N \left( R \cdot C_{out} + \frac{R \cdot X_{i+1} \cdot C_{in}}{X_i} \right)$$

★ parameter  $\gamma = \frac{C_{out \text{ base}}}{C_{in \text{ base}}}$

$$\text{Total delay} = \sum_{i=1}^N \left( R \cdot C_{out} + \frac{R \cdot C_{out} \cdot X_{i+1}}{\gamma \cdot X_i} \right)$$

$$\text{total delay} = N \cdot R \cdot C_{\text{out}} \sum_{i=1}^N \left( 1 + \frac{x_{i+1}}{\gamma x_i} \right) = N \cdot R \cdot C_{\text{out}} \sum_{i=1}^N \left( 1 + \frac{C_{\text{in},i+1}}{C_{\text{in},i}} \right)$$

remember:  $C_{\text{in},N} = C_{\text{load}}$  (only  $N-1$  unknowns)

$$\frac{x_{i+1}}{x_i} = \frac{C_{\text{in},i+1}}{C_{\text{in},i}}$$

more useful term for non-inverters

Minimize total delay by taking  $N-1$  partial derivatives and making all  $= \phi$ .

$$\frac{\partial}{\partial C_{\text{in},j}} \left( \text{total delay} \right) = \phi \quad \text{for } j = [1 \dots N-1]$$

→ expand the series to see this pattern.

$$\dots \underbrace{\left( 1 + \frac{C_{\text{in},j-1+1}}{\gamma C_{\text{in},j-1}} \right)}_{\uparrow} + \underbrace{\left( 1 + \frac{C_{\text{in},j+1}}{\gamma C_{\text{in},j}} \right)}_{\uparrow} + \underbrace{\left( 1 + \frac{C_{\text{in},j+1+1}}{\gamma C_{\text{in},j+1}} \right)}_{\uparrow}$$

only these terms stay with  $\frac{\partial}{\partial C_{\text{in},j}}$  derivative

$$\frac{\partial}{\partial C_{\text{in},j}} \left( \frac{C_{\text{in},j}}{\gamma C_{\text{in},j-1}} + \frac{C_{\text{in},j+1}}{\gamma C_{\text{in},j}} \right) = \frac{1}{\gamma C_{\text{in},j-1}} - \frac{C_{\text{in},j+1}}{\gamma (C_{\text{in},j})^2} = \phi$$

solutions are

$$\frac{1}{\gamma C_{\text{in},j-1}} = \frac{C_{\text{in},j+1}}{\gamma (C_{\text{in},j})^2}$$

$$C_{\text{in},j} = \sqrt[C_{\text{in},j-1} \cdot C_{\text{in},j+1}]{\text{geometric mean}}$$



$$\frac{C_{\text{in},j}}{C_{\text{in},j-1}} = \frac{C_{\text{in},j+1}}{C_{\text{in},j}}$$

$$\frac{f_j}{f_{j-1}} = \frac{f_{j+1}}{f_j}$$

⇒ all  $f_j$ 's must be equal

$$C_{in(N-1)+1} = C_{load} \quad \text{last capacitor is the load}$$

$$\frac{C_{load}}{C_{in_1}} = f_1 \cdot f_2 \cdots f_N = f^N = F = GH$$

↑  
all 1 for inverters

now we can write:

$$\text{total delay} = R \cdot C_{out} \cdot N \cdot \left(1 + \frac{\gamma}{\phi}\right)$$

$$\text{and } N = \frac{\ln F}{\ln f}$$

$$\text{total delay} = R \cdot C_{out} \cdot \frac{\ln F}{\ln f} \left(1 + \frac{\gamma}{\phi}\right)$$

what is the best  $f$ ?  $\rightarrow \text{derivative} = 0$ !

$$\frac{d}{df} (\text{total delay}) = R \cdot C_{out} \cdot \frac{d}{df} \left( \frac{\ln F}{\gamma} \left( \frac{\gamma}{\ln f} + \frac{f}{\ln f} \right) \right)$$

$$= R \cdot C_{out} \cdot \frac{\ln F}{\gamma} \left[ \frac{-\gamma}{f \cdot \ln^2(f)} + \underbrace{\frac{\ln(f)-1}{\ln^2(f)}}_{-\frac{\gamma}{f} + \frac{\ln(f)-1}{\ln^2(f)}} \right] = 0$$

$$-\frac{\gamma}{f} + \frac{\ln(f)-1}{\ln^2(f)} = 0$$

$\star$

$$\ln f = 1 + \frac{\gamma}{f}$$

$$f_{opt} = \exp \left( 1 + \frac{\gamma}{f_{opt}} \right)$$

no closed-form solution  
unless  $\gamma = \phi \approx$

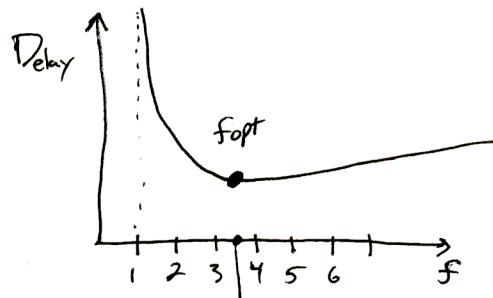
$$\gamma = f(\ln f - 1) \quad \leftarrow \text{plot this and swap the axes!}$$

Find  $f$  for a few values of  $\gamma$ :

$\gamma$	$f_{opt}$
$\phi$	$2.72 (=e)$
1	3.59
2	4.32

← most processes have  $\frac{C_{out}}{C_{in}} = \gamma \approx 1$

plot total delay vs.  $f$  ( $\text{for } \gamma=1$ )



$$N_{opt} = \frac{\ln F}{\ln f_{opt}}$$

$$f_{opt} = F^{1/N_{opt}}$$

Observations about this plot:

- Choosing  $f$  smaller than  $f_{opt}$ : more stages (more area and power) ↗ increasing delay ↗
- Choosing  $f$  larger than  $f_{opt}$ : less stages less area and power ↘ not much delay increase ↘

⇒ Usually, round to a smaller  $N$

and use a larger  $f$

~~As~~ This is the origin of "fan-out of 4", or stage effort  $f=4$   
as a good rule-of-thumb  
Logical Effort terminology

(sometimes  $N$  needs to be even or odd for)  
logic function purposes

